GPS/FMS RNAV TRANSITION TO FINAL APPROACH (OVERLAY TO RADAR VECTOR PATTERN)

Route Description

		CODING		DISPLAY	
CEL 27L					
CEL	F070-; K250-	N 52 35 22.53	E 010 01 46.04	N 52 35.4	E 010 01.8
DV500	L	N 52 37 23.06	E 009 50 55.74	N 52 37.4	E 009 50.9
DV501	K220-; L	N 52 37 34.28	E 009 44 22.35	N 52 37.6	E 009 44.4
DV502	L	N 52 32 35.00	E 009 44 02.07	N 52 32.6	E 009 44.0
DV565		N 52 31 22.39	E 010 23 17.06	N 52 31.4	E 010 23.3
ODINI	A3000+; K170+	N 52 26 49.81	E 009 56 53.49	N 52 26.8	E 009 56.9
FINAL APPROACH 27L [ILS - LOC - RNP]					
CEL 27R					
CEL	F070-; K250-	N 52 35 22.53	E 010 01 46.04	N 52 35.4	E 010 01.8
DV500	L	N 52 37 23.06	E 009 50 55.74	N 52 37.4	E 009 50.9
DV501	K220-; L	N 52 37 34.28	E 009 44 22.35	N 52 37.6	E 009 44.4
DV502	L	N 52 32 35.00	E 009 44 02.07	N 52 32.6	E 009 44.0
DV565		N 52 31 22.39	E 010 23 17.06	N 52 31.4	E 010 23.3
XAVER	A3000+; K170+	N 52 27 36.34	E 009 56 15.69	N 52 27.6	E 009 56.3
FINAL APPROACH 27R [ILS - LOC - NDB - RNP]					
NIE 27L					
NIE	F110-; K250-	N 52 37 33.21	E 009 22 19.17	N 52 37.6	E 009 22.3
DV502	K220-; L	N 52 32 35.00	E 009 44 02.07	N 52 32.6	E 009 44.0
DV565		N 52 31 22.39	E 010 23 17.06	N 52 31.4	E 010 23.3
ODINI	A3000+; K170+	N 52 26 49.81	E 009 56 53.49	N 52 26.8	E 009 56.9
FINAL APPROACH 27L [ILS - LOC - RNP]					
NIE 27R					
NIE	F110-; K250-	N 52 37 33.21	E 009 22 19.17	N 52 37.6	E 009 22.3
DV502	K220-; L	N 52 32 35.00	E 009 44 02.07	N 52 32.6	E 009 44.0
DV565		N 52 31 22.39	E 010 23 17.06	N 52 31.4	E 010 23.3
XAVER	A3000+; K170+	N 52 27 36.34	E 009 56 15.69	N 52 27.6	E 009 56.3
FINAL APPROACH 27R [ILS - LOC - NDB - RNP]					

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