

HANNOVER

WAY POINT LIST

GPS/FMS RNAV TRANSITION TO FINAL APPROACH (OVERLAY TO RADAR VECTOR PATTERN)

Route Description

CODING

DISPLAY

NIE 09L

NIE	F080-; K250-	N 52 37 33.21	E 009 22 19.17	N 52 37.6	E 009 22.3
DV400	K220-; R	N 52 37 15.77	E 009 33 34.40	N 52 37.3	E 009 33.6
DV460	R	N 52 32 52.40	E 009 33 15.55	N 52 32.9	E 009 33.3
DV465		N 52 33 40.07	E 009 00 30.92	N 52 33.7	E 009 00.5
DESIM	A3000+; K170+	N 52 28 28.31	E 009 24 52.09	N 52 28.5	E 009 24.9

FINAL APPROACH 09L [ILS - LOC - NDB - RNP]

NIE 09R

NIE	F080-; K250-	N 52 37 33.21	E 009 22 19.17	N 52 37.6	E 009 22.3
DV400	K220-; R	N 52 37 15.77	E 009 33 34.40	N 52 37.3	E 009 33.6
DV460	R	N 52 32 52.40	E 009 33 15.55	N 52 32.9	E 009 33.3
DV465		N 52 33 40.07	E 009 00 30.92	N 52 33.7	E 009 00.5
PIXEL	A3000+; K170+	N 52 27 40.69	E 009 26 23.04	N 52 27.7	E 009 26.4

FINAL APPROACH 09R [ILS - LOC - RNP]

DLE 27L

DLE	F080-; K250-	N 52 15 01.15	E 009 53 00.58	N 52 15.0	E 009 53.0
DV581	R	N 52 22 18.44	E 009 53 43.01	N 52 22.3	E 009 53.7
DV582	K220-	N 52 22 01.91	E 010 02 50.44	N 52 22.0	E 010 02.8
DV585		N 52 21 24.06	E 010 22 25.61	N 52 21.4	E 010 22.4
ODINI	A3000+; K170+	N 52 26 49.81	E 009 56 53.49	N 52 26.8	E 009 56.9

FINAL APPROACH 27L [ILS - LOC - RNP]

DLE 27R

DLE	F080-; K250-	N 52 15 01.15	E 009 53 00.58	N 52 15.0	E 009 53.0
DV581	R	N 52 22 18.44	E 009 53 43.01	N 52 22.3	E 009 53.7
DV582	K220-	N 52 22 01.91	E 010 02 50.44	N 52 22.0	E 010 02.8
DV585		N 52 21 24.06	E 010 22 25.61	N 52 21.4	E 010 22.4
XAVER	A3000+; K170+	N 52 27 36.34	E 009 56 15.69	N 52 27.6	E 009 56.3

FINAL APPROACH 27R [ILS - LOC - NDB - RNP]